

Sponsored by

Track 4 Foot-mounted IMU

Miguel Ortiz, Ni Zhu





2 teams

Overall description



- Shopping mall Atlantis
- \sim 1.2 km walk / \sim 45 min
- Indoor (95%), outdoor (5%)
- Stairs

- Lifts / Escalator / Travelator
- 3 breaks ~15s
- 4 floors: (R-1) R0 R1 R2

• NOVELTY: quasi RealTime condition!

Team Name	Country	Organization
Silk-Road Reckoners	China	-School of Electronic and Information Engineering, Beihang University
ICT-BUPT	China	-School of Computer Science, Beijing University of Posts and Telecommunications -Institute of Computing Technology, Chinese Academy Sciences

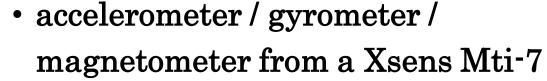




Overall description

• Inputs from ULISS:











- barometer from BMP280 sensor
- temperature sensor



nav4you





Ubiquituous Localization with Inertial Sensors and Satellites
ULISS sensor (by Team GEOLOC)



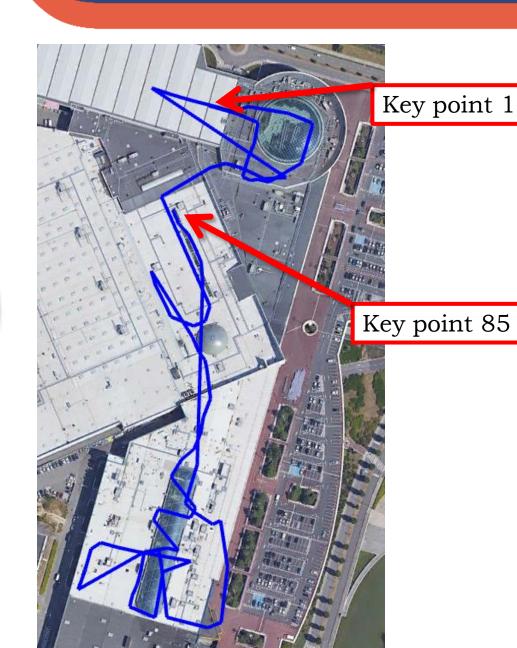


Objective

- Re-build the trajectory realized in Sept 2021
- Starting from a known point
- At specific given timestamps
- 83 key points were evaluated:

```
304306944, -1.6312051066, 47.2228866914, 0, 1
304318212, -1.6312639579, 47.2230060176, 0, 2
304341237, -1.6311166197, 47.2232588847, 0, 3
304395079, -1.6313360420, 47.2234883288, 1, 4
304399422, -1.6313874860, 47.2235097003, 1, 5
...
305881902, -1.6309329730, 47.2253019451, 0, 65
305925620, -1.6308880959, 47.2253704618, 0, 66
305963826, -1.6308375003, 47.2255163809, 0, 67
306012968, -1.6302977366, 47.2254982935, 0, 68
```





Objective

From: IMU (Acc, Gyro), MAG, GNSS, BARO sensors

ROTA, 310061.998129000, 4.12264, -0.11782, 1.95676
ACCE, 310061.998358000, -5.08618, -8.94552, 7.51071
ROTA, 310062.003132000, 3.99029, -0.171031, 2.0577
ACCE, 310062.003346000, -4.81856, -8.90485, 7.69366
MAGN, 310062.006216000, 0.834387, 0.496714, -0.539119
GOBS, 310062.007000000, GO7 24984599.602 9
GOBS, 310062.007000000, R23 22411544.490 9
GOBS, 310062.007000000, GO2 24973888.141 9
ROTA, 310062.008136000, 3.82733, -0.196311, 2.14405
ACCE, 310062.008333000, -4.42163, -8.88965, 8.09426
ROTA, 310062.013140000, 3.65192, -0.187157, 2.20612
ACCE, 310062.013321000, -3.98475, -9.17112, 8.48837

Compute:



At specific timestamps

In quasi Realtime condition through the Evaal web API



Track4 Call For Competition

https://evaal.aaloa.org/images/2021/IPIN2021 Track4 CallForCompetition v2.1.pdf





Track description







Starting point R-1 (indoor - static)

Lift (R-1) \rightarrow (R2)

Travelator $R2 \rightarrow R0$ (walker static)



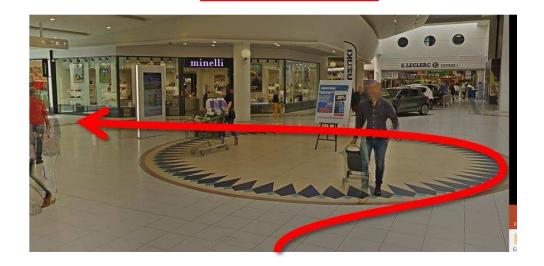


Track description



Long straight walk

Wide area







Track description

Travelator $R0 \rightarrow R-1$ (walking)



IPIN 2021
ELEVENTH INTERNATIONAL CONFERENCE ON INDOOR POSITIONING
AND INDOOR NAVIGATION
29 Nov. – 2 Dec. 2021, Lloret de Mar, Spain

Wide area (running)



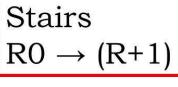
Miguel Ortiz, Ni Zhu

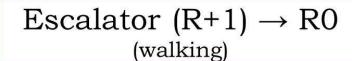
Travelator (R-1) \rightarrow R0 (walker static)



Track description

$$R0 \rightarrow (R-1) \rightarrow R0$$
 (outdoor)









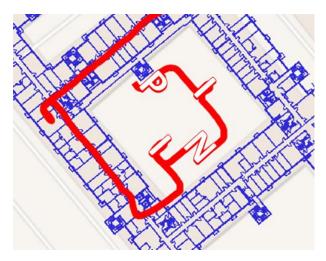


frontiers



Track description

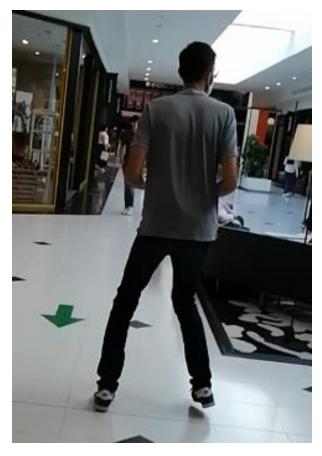
surprise IPIN2021: some new activities (side walking / running)



IPIN2019



IPIN2020



IPIN2021



frontiers

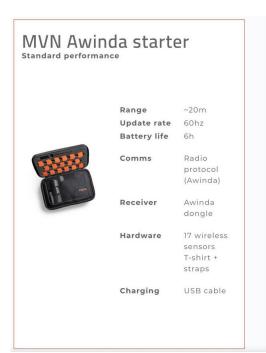




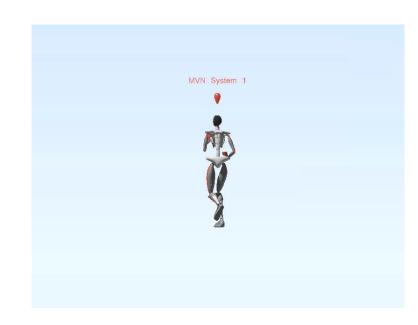


IPIN2021 news

- AWINDA system used in // (ZUPT ref)
- Availability of the data under discussion













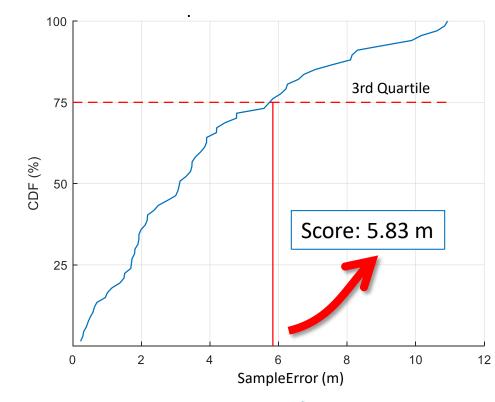
Evaluation



3D geo-referenced points cloud (Lat/Long/Height)

Accuracy Score = $3rdQuartile{SampleError(R_i, E_i)}$ Where:

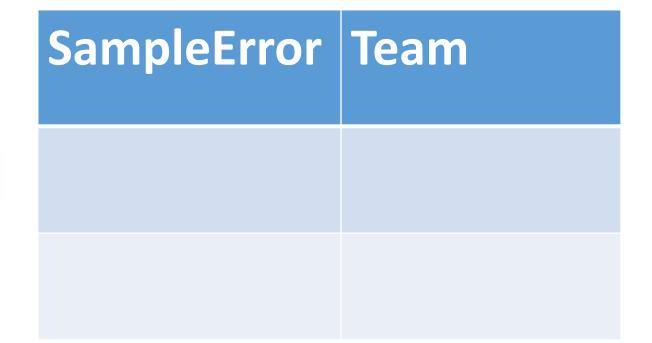
SampleError(R_i, E_i) = Distance(R_i, E_i) + (penalty × floorfail)







Results







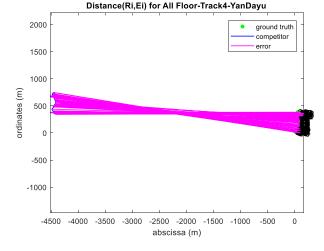




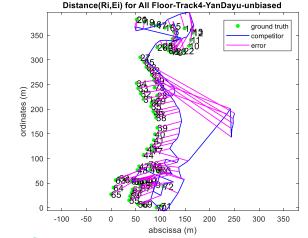
Results



biased (official result)



un-biased (by track chair)





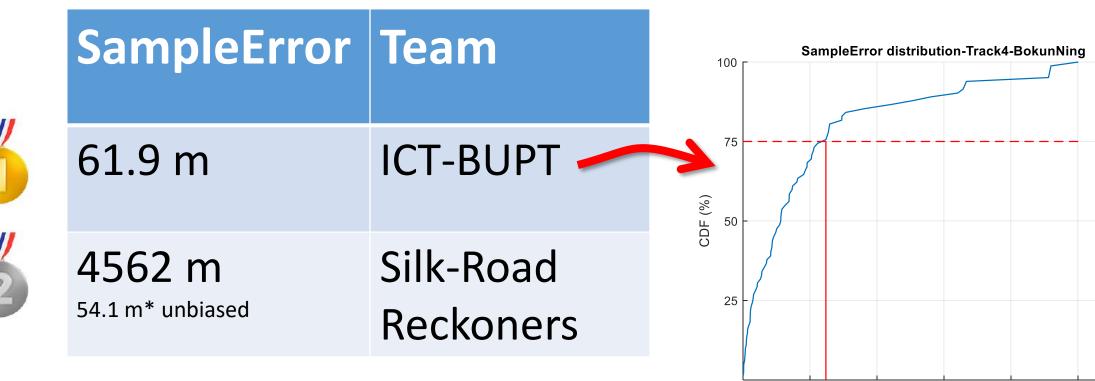


150

Horizontal Position Error (m)

50

Results







250

300

Results

CONGRATULATIONS



ICT-BUPT





Bokun Ning, Bao Linfeng





Results

Evolution of best score of Track4 over last 4 years

